Current and Future Developments

Parallel Storage Systems



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2023-07-10

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Current and Future Developments

Review

Motivation

Hardware

Software

- Which technology improves at the fastest rate?
 - Storage capacity
 Storage throughput
 - 3. Network throughput
 - 4. Memory throughput
 - 5. Computation

- Which overhead does deduplication introduce?
 - 1. Processor utilization
 - 2. Main memory utilization
 - 3. Storage utilization
 - 4. All of the above

- Which overhead does compression introduce?
 - 1. Processor utilization
 - 2. Main memory utilization
 - 3. Storage utilization
 - 4. All of the above

- Which compression algorithm would you use for archival?
 - 1. lz4
 - 2. lz4hc
 - 3. xz
 - 4. zstd

Current and Future Developments

Review

Motivation

Hardware

Software

- Supercomputers are getting more powerful all the time
 - Storage systems get more capacity and throughput
 - Scalability requirements are increased by higher process counts
- · Amount of data keeps growing
 - Supercomputers have more than 1 PB of main memory
 - Even at 1 TB/s, a checkpoint would take more than 15 minutes
- Storage hardware is becoming more efficient
 - Software has to keep up with efficiency increases
 - I/O stacks have traditionally been heavy-weight

- One file per process does not scale
 - TaihuLight has more than 40,000 compute nodes
 - Large systems can have more than 10,000,000 cores
- POSIX is still widely used
 - · Strict coherence and consistency requirements
 - · Changes have to be visible globally immediately
- Traditional file systems are often implemented in the kernel
 - Other components already bypass the kernel due to performance
 - For example, InfiniBand uses kernel bypass to reduce overhead

Current and Future Developments

Review

Motivation

Hardware

Software

- · Memory and storage hierarchy has several levels
 - L1, L2, L3 cache, RAM, SSD, HDD and tape
- Huge latency gap between RAM and SSD
 - Significant performance degradation if data is not in RAM
 - · Network causes additional overhead in distributed contexts
- · Gap is especially pronounced on supercomputers
 - Data is either locally in RAM or in the parallel distributed file system
- · New technologies are supposed to close this gap
 - NVRAM, NVMe, 3D XPoint etc.
 - · Introduces additional hierarchy levels

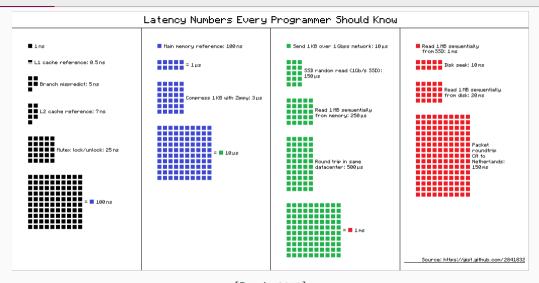
Very low latency between CPU and caches
 One cycle takes 0.5–0.33 ns (2–3 GHz)
 RAM is already significantly slower

Level	Latency
L1 Cache	≈ 1 ns
L2 Cache	≈ 5 ns
L3 Cache	≈ 10 ns
RAM	≈ 100 ns

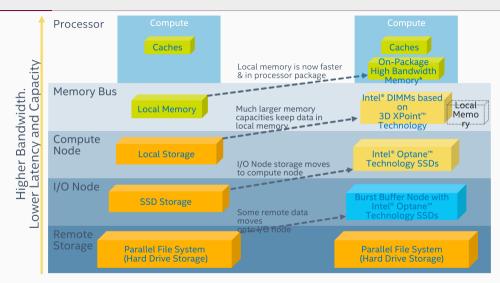
[Bonér, 2012] [Huang et al., 2014]

	Level	Latency	
	L1 Cache	≈ 1 ns	
 Very low latency between CPU and caches One cycle takes 0.5–0.33 ns (2–3 GHz) 	L2 Cache	≈ 5 ns	
	L3 Cache	≈ 10 ns	
RAM is already significantly slower	RAM	≈ 100 ns	
• There is a factor of 1,000 between RAM and SSD			
 Network latency in distributed systems 			
	SSD	≈ 100,000 ns	
	HDD	≈ 10,000,000 ns	
	Таре	$\approx 50,000,000,000 \text{ ns}$	
	[Bonér, 201	[Bonér, 2012] [Huang et al., 2014]	

	Level	Latency
	L1 Cache	≈ 1 ns
 Very low latency between CPU and caches One cycle takes 0.5-0.33 ns (2-3 GHz) RAM is already significantly slower There is a factor of 1,000 between RAM and SSD Network latency in distributed systems Multiple intermediate levels in future systems NVRAM will also offer novel approaches 	L2 Cache	≈ 5 ns
	L3 Cache	≈ 10 ns
	RAM	≈ 100 ns
	NVRAM	≈ 1,000 ns
	NVMe	≈ 10,000 ns
	SSD	≈ 100,000 ns
	HDD	≈ 10,000,000 ns
	Tape	≈ 50,000,000,000 ns
	[Bonér, 201	2] [Huang et al., 2014]

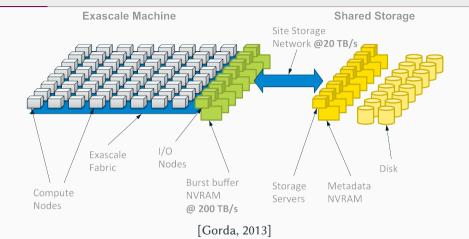


[Bonér, 2012]



Exascale





- $\ensuremath{\mathsf{I/O}}$ nodes are equipped with burst buffers and close to the compute nodes
- Network between I/O nodes and storage servers is slower

- I/O nodes can take over additional tasks
 - · Certain computations and transformations
 - Scheduling and aggregating I/O operations
- Data can be reorganized for more efficient access
 - · For instance, row- and column-wise storage
 - · Requires knowledge about the underlying data format
- Computational power is higher closer to the compute nodes
 - Makes the most sense while data is being produced
 - Care has to be taken to not influence performance negatively

- I/O behavior is often not uniform.
 - Applications compute and then write a shared checkpoint
 - High I/O load during checkpointing, no I/O activity afterwards
- I/O spikes can slow down applications
 - Multiple applications performing I/O in parallel
 - Storage systems are usually not designed to handle high spikes
 - Example Mistral: $\approx 20 \, \text{TB/s}$ (compute nodes) vs. $\approx 0.5 \, \text{TB/s}$ (file system)
- Guaranteeing high throughput can become expensive
 - HDDs for capacity, SSDs for throughput (and latency)
 - · Network introduces additional performance constraints

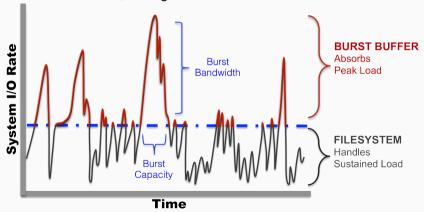
- Applications do not coordinate their I/O phases
 - Could be used to keep the I/O load balanced
 - Very complex to realize since it depends on timing etc.
 - Involves the application, the scheduler and the file system
- File systems are usually shared resources
 - There are quality of service approaches for I/O
 - · Applications could communicate their requirements to the scheduler

- How much storage bandwidth is used on average?
 - 1. 99 %
 - 2. 50 %
 - 3. 33 %
 - 4. 5%

Burst Buffers... Hardware

Analysis of a major HPC production storage system

- 99% of the time, storage BW utilization < 33% of max
- 70% of the time, storage BW utilization < 5% of max



[Vildibill, 2015]
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Burst Buffers... Hardware

- Compute nodes achieve higher throughput
 - Up to 100 GiB/s instead of 10-20 GiB/s
 - No change for slow applications
- · Applications finish earlier
 - Can spend more time performing computation

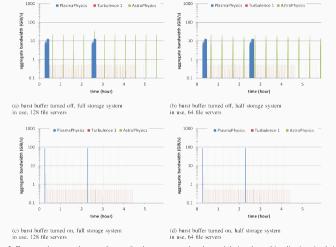


Fig. 5: Ten second average data transfer rate for the compute nodes observed during the multiapplication simulations

[Liu et al., 2012]

Burst Buffers...

Hardware

- No throughput changes on storage servers
 - Depends on number of storage servers
- · Utilization increased
 - Idle times are reduced

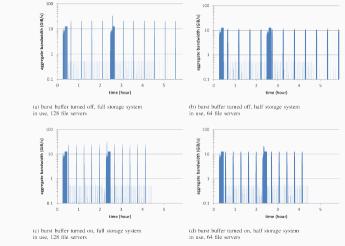


Fig. 6: Ten second average data transfer rate for the external storage system observed during the multiapplication simulations

[Liu et al., 2012]

- Burst buffers allow saving significant amounts of money
 - Storage systems do not have to be designed to handle high I/O spikes
 - Allows using a smaller storage system or one with less throughput
- · Might also allow using slower storage technologies
 - Ethernet instead of InfiniBand (or cheaper InfiniBand)
 - HDDs with 5,400 RPM instead of 7,200 RPM
- Makes it possible to increase device utilization
 - Burst buffers can also absorb problematic I/O patterns such as random I/O
 - I/O operations are "pre-processed" and then forwarded to storage system

- Data reduction etc. can be compute-intensive
 - Deduplication, compression etc. require compute power
- GPUs are often not suitable since the PCIe bus limits I/O
 - At most \approx 16 GB/s (PCle 3.0) or \approx 32 GB/s (PCle 4.0)
- · Several acceleration interfaces could be used in the future
 - Intel's processors support QuickAssist with DEFLATE and LZS (since Haswell)
 - · Intel is working on socketed accelerators, which can access RAM directly
 - PCle 5.0 with $\approx 64 \, \text{GB/s}$

Current and Future Developments

Review

Motivation

Hardware

Software

- Classical parallel distributed file systems are not enough anymore
 - Should serve as the basis for future storage systems
 - They are the only production-ready solution at the moment
- Lustre is in active development [Gorda, 2016]
 - Encryption
 - Compression
 - Complex data layouts
 - Further I/O optimizations

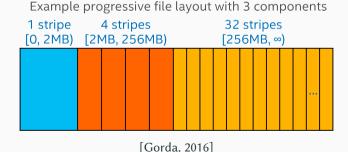
- Encryption is increasingly important
 - Governments, military, classified research etc.
- Support for multiple access levels is necessary
 - Unclassified, confidential, secret, top secret
 - Data is not allowed to be transferred across levels
- Authentication and authorization are important components
 - Can be implemented using Kerberos, which is widely used
- · Data is encrypted in flight to prevent unauthorized access
 - · Support for encryption at rest has been recently added

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Lustre...

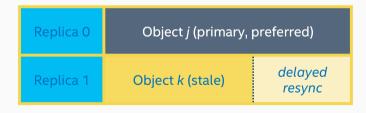
Software

- Applications and data formats have different data distribution requirements
 - Small files should only be distributed across a few OSTs
 - Large files should be distributed across as many OSTs as possible
- · Lustre can adapt striping parameters intelligently
 - · Goal is to minimize overhead and maximize performance



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- Replicating files can be useful for popular data
 - Replication can be set on a per-file basis
 - Can be used to achieve high availability, robustness, higher read throughput, migration across storage classes etc.
- · Synchronization is done in the background



Overlapping (mirror) layout

[Gorda, 2016]

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- · Small files should be stored directly on the MDT
 - Similar to optimizations in ext4, ZFS etc.
 - Can reduce communication overhead by not talking to OSTs
 - Potential for further optimizations such as readahead
- MDTs are typically optimized for small accesses
 - Large accesses still handled by the OSTs
- Data might have to be migrated when files grow

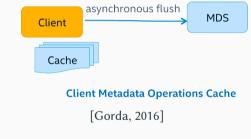


layout, lock, attributes, read

Small file IO directly to MDS

[Gorda, 2016]

- Metadata operations are usually small
 - Corresponds to high network overhead
- Caching allows aggregating multiple operations
 - Requires locks to avoid conflicts from concurrent operations
 - Example: Lock a directory and create many files within it



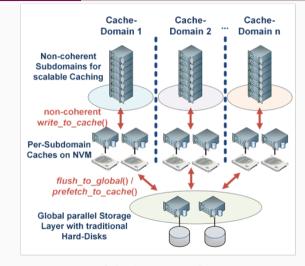
Software

- POSIX is still a major limitation for I/O performance and scalability
 - POSIX is very portable but poses a performance bottleneck
- There are a few existing alternatives
 - MPI-IO still uses the POSIX interface anyway
 - POSIX file systems are used locally in many cases
- · New interfaces and semantics are being investigated
 - Object stores often provide enough features for HPC I/O
 - · When using POSIX, its semantics is usually relaxed

- One idea is to not provide global coherence anymore
 - File system is instead partitioned into non-coherent zones
 - · For instance, using burst buffers and forwarders
- Example: Cache domains as used in BeeGFS
 - Applications are running in different domains
 - Data is first written to the non-coherent cache
 - Caches can be located in a local NVRAM
 - Data is then migrated from the cache into the file system

POSIX... Software

- · Non-coherent domains can scale
 - Data does not have to be synchronized across all applications
 - Applications typically do not access same output data
- · Flushed to file system afterwards
 - · Similar to burst buffer concept



[ThinkParQ, 2017]

- DAOS is a holistic approach for a new storage stack
 - Distributed Application Object Storage (DAOS)
- DAOS supports multiple storage models
 - · Arrays and records as base objects
 - Objects consist of arrays and records (key-array)
 - Containers contain objects
 - · Storage pools consist of containers
- DAOS supports versioning data
 - Operations are performed as transactions
 - · Transactions are merged and persisted as epochs
- · Makes extensive use of modern storage technologies

- How much overhead does the I/O software stack introduce?
 - 1. 99 %
 - 2. 50 %
 - 3. 33 %
 - 4. < 1 %

DAOS...

Software

- I/O latencies are becoming problematic
 - Additional software layers introduce overhead
- I/O granularity needs to be adapted
 - Often still at 1 MiB, soon 16 MiB, which might cause additional conflicts
 - · Network and storage devices require larger accesses



msec vs. μsec μsec vs. μsec

[Dilger, 2017]

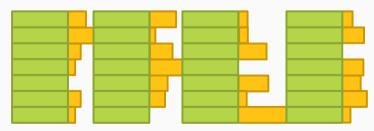
nsec vs. µsec

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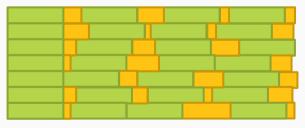
DAOS...

- I/O is typically performed synchronously
 - Applications have to wait for the slowest process/thread
 - · Results in waiting times in which processors are idle
- I/O variability is the norma
 - · Storage systems are shared resources, others can influence performance
 - Quality of service or other performance guarantees are rare



[Gorda, 2013]

- I/O should happen asynchronously to reduce idle times
 - · Processes/threads do not have to wait for others anymore
- Raises the problem of file consistency
 - Currently, a file is consistent when all processes have finished I/O
 - · File is only consistent as long as it is not modified again

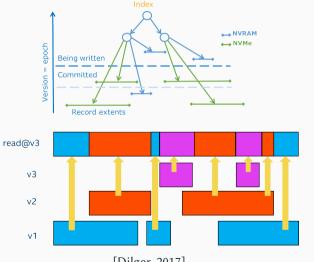


[Gorda, 2013]

Software

DAOS...

- · Solution: Transactions and epochs
 - Operations are performed in transactions
 - Multiple transactions are merged into an epoch
- · Epochs are globally consistent
 - Epochs are on a per-object basis
 - Eliminates coherence problems when reading data
 - Epochs can use copy on write for efficiently storing versions

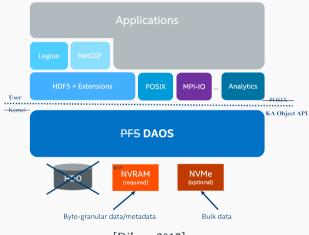


[Dilger, 2017]

- DAOS supports several I/O interfaces natively
 - Makes supporting legacy applications much easier
- HDF5 is mapped onto DAOS's objects
 - An HDF5 file corresponds to a DAOS container
 - Mapping can be used to reorganize data for efficient access etc.
- Other I/O interfaces can be added on top
 - · POSIX and MPI-IO for legacy applications
 - Big data interfaces for MapReduce etc.
 - S3, NFS, block devices etc.

DAOS... Software

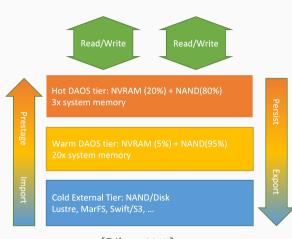
- Functionality moved to user space
 - Kernel bypass to eliminate costly context switches
- Software stack for NVRAM/NVMe
 - HDDs are controlled by existing file systems such as Lustre



[Dilger, 2017]

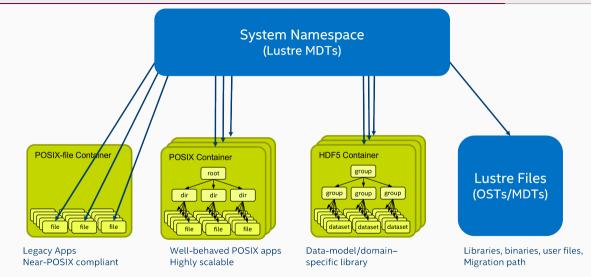
DAOS...

- · Hot and warm data managed by DAOS
 - · Cold data managed by file system
- Prestage migrates data into cache
 - · Persist stores data
- Import/export to/from cold storage
 - File systems like Lustre
 - Object stores like S3



[Dilger, 2017]

DAOS... Software



[Dilger, 2017]
Current and Future Developments

- Big data technologies are widely used
 - Big data software is often not as performant as HPC software
- Hadoop is an important big data component and uses HDFS
 - Data is copied to local storage devices
 - Communication happens via HTTP
- · HPC software increasingly supports big data use cases
 - · Lustre, OrangeFS etc.
- Problem: Two completely separate software stacks

Big Data...

- Big data often uses commodity hardware
 - Ethernet, local storage, HTTP etc.
- HPC tuned for high performance
 - InfiniBand, dedicated storage nodes, accelerators etc.

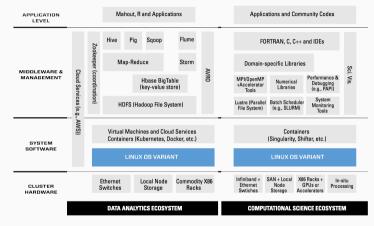
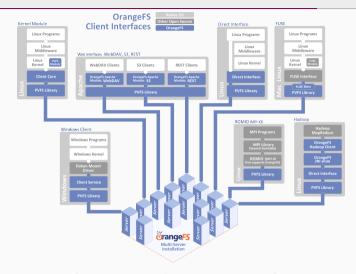


Figure 1: Different software ecosystems for high-end Data Analytics and for traditional Computational Science. [Credit: Reed and Dongarra [66]]

[Russell, 2018] [Andre et al., 2018]

Big Data...

- OrangeFS offers several I/O interfaces
 - POSIX compatibility via kernel module, FUSE or direct interface
 - HPC support via MPI-IO
 - · Web interfaces for cloud
 - Big data support using Hadoop interface



[OrangeFS Development Team, 2021]

Big Data... Software

- HDFS uses node-local storage
 - Best case: Data can be accessed locally
- OrangeFS uses storage servers
 - Data is always accessed remotely

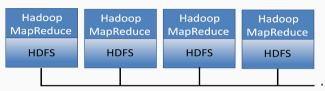


Fig. 2: Typical Hadoop with HDFS local storage (HDFS in short).

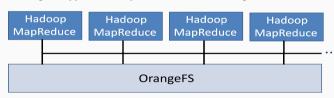


Fig. 3: Hadoop with the OrangeFS dedicated storage (OFS in short).

[Li et al., 2016]

- Approaches from the big data and cloud fields are also interesting for HPC
 - · Elasticity could allow adapting file systems dynamically
 - Adding and removing file system servers on demand
- Object stores are being used for storing data
 - · POSIX file system functionalities are often not required
 - MPI-IO's features can be mapped to object stores

Outline

Current and Future Developments

Review

Motivation

Hardware

Software

Summary

- New hardware technologies will change the storage stack
 - New hierarchy levels provided by NVRAM and NVMe
 - Systems will become complexer but also more performant
 - Burst buffers offer possibilities for reducing costs
 - Data transformation can be deployed across the stack
- Current I/O software is being redesigned from the ground up
 - Applications can continue using existing high-level interfaces
 - POSIX limits performance and is often not necessary
 - New approaches from the big data and cloud fields will be integrated

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